

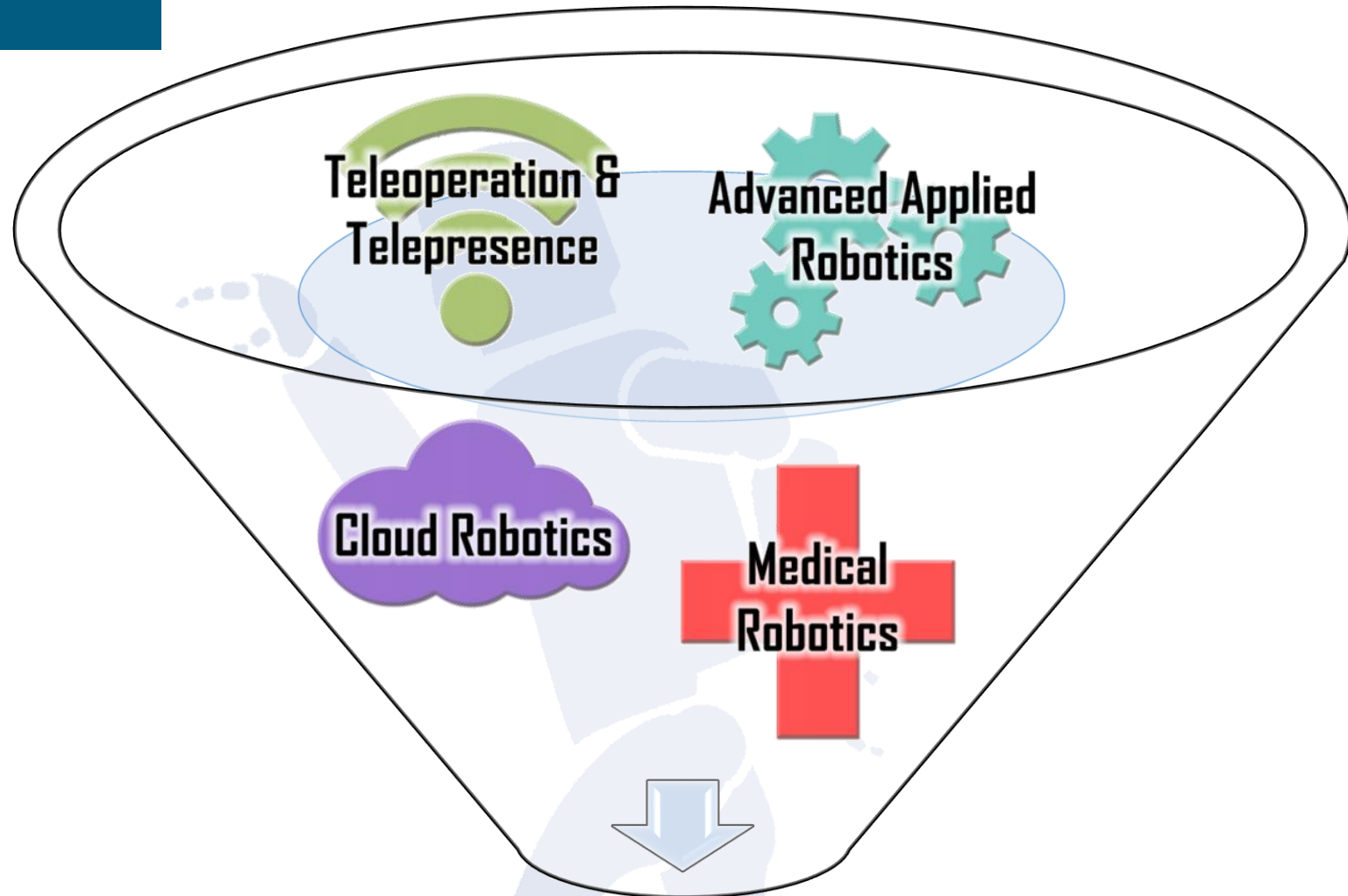
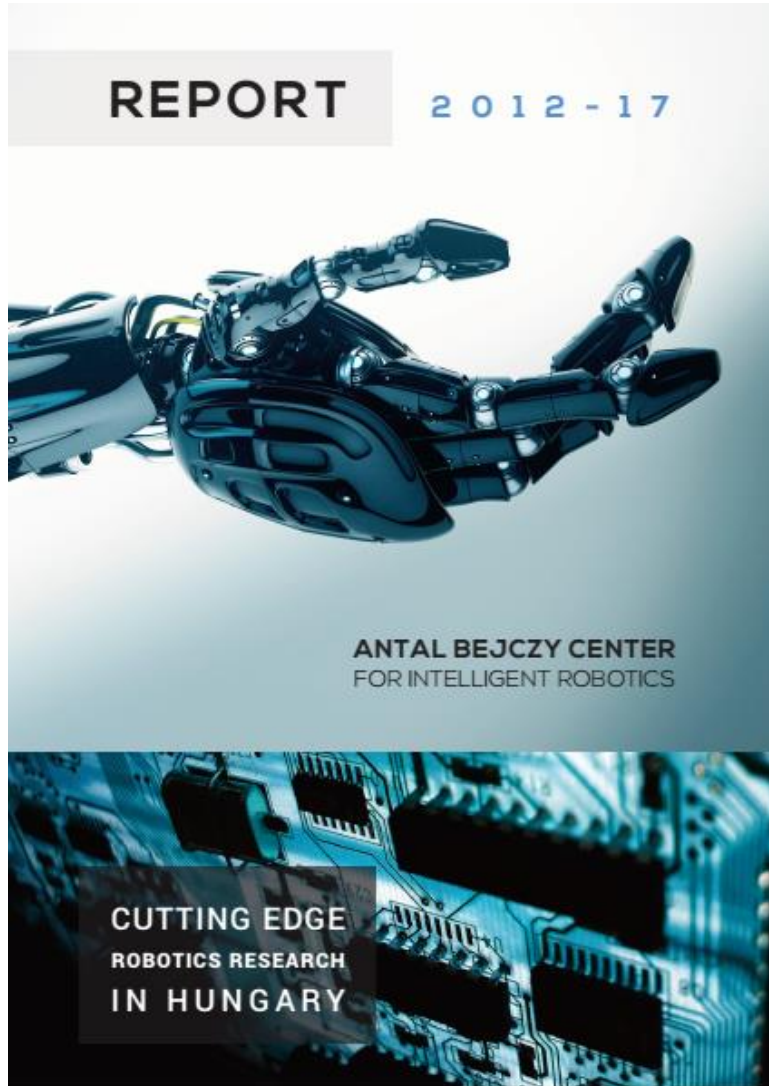


Infrastructure and expertise for successful Robotics 4.0 pilot projects in food Industry

Péter Galambos, PhD
Antal Bejczy Center for Intelligent Robotics

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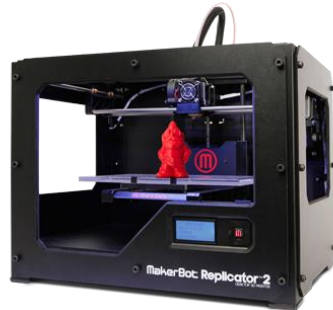
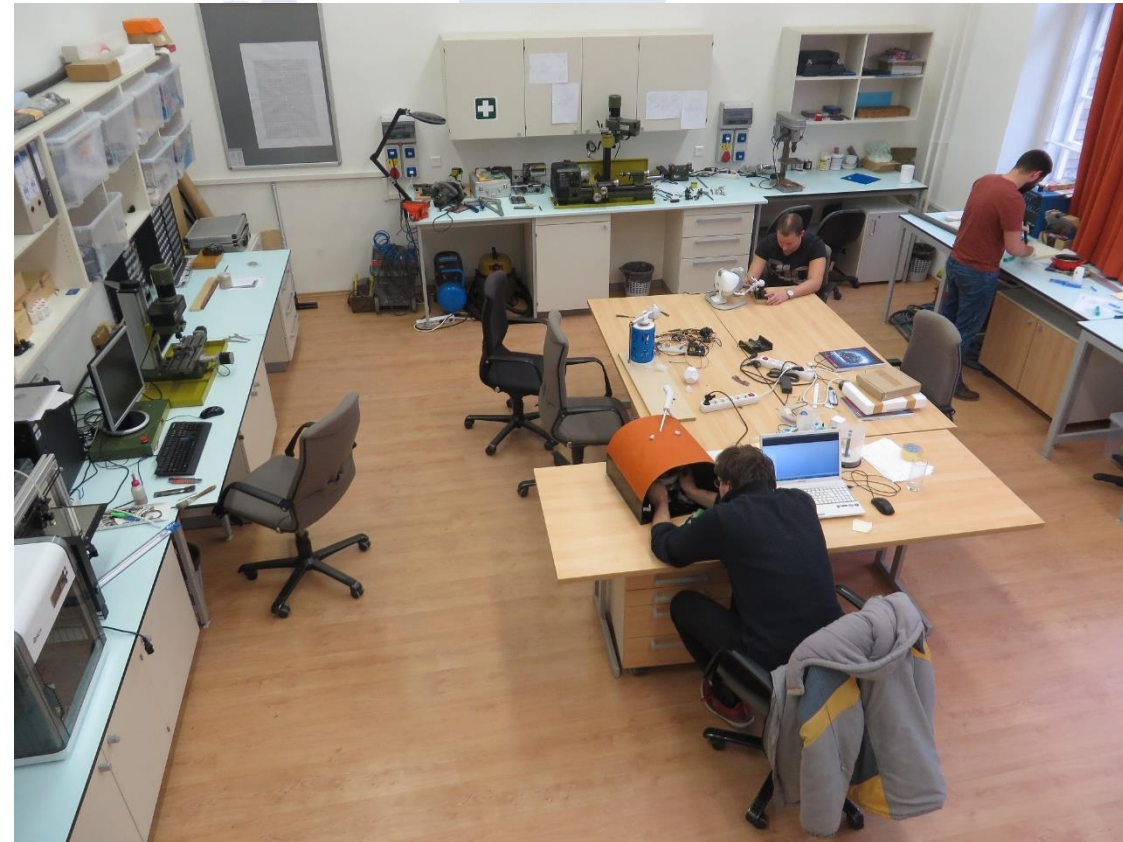
Industrial and Medical Cyber Physical Systems



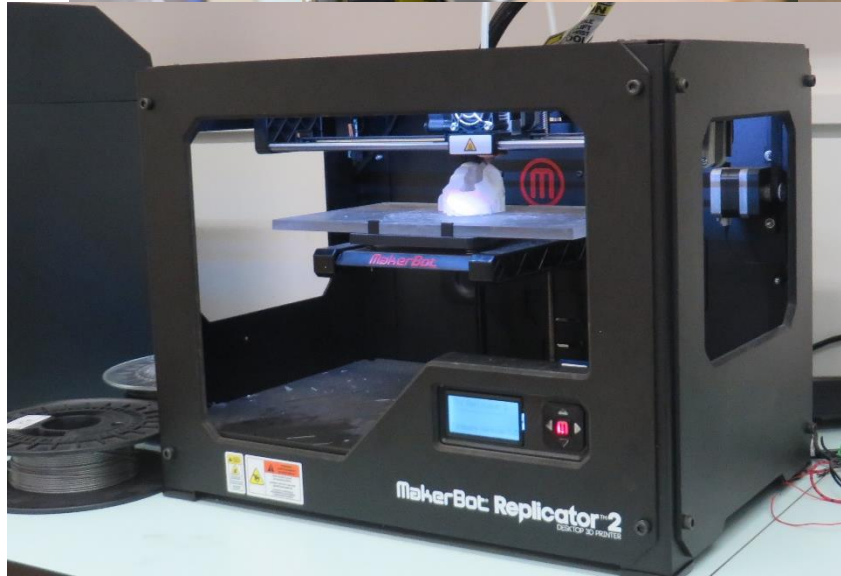
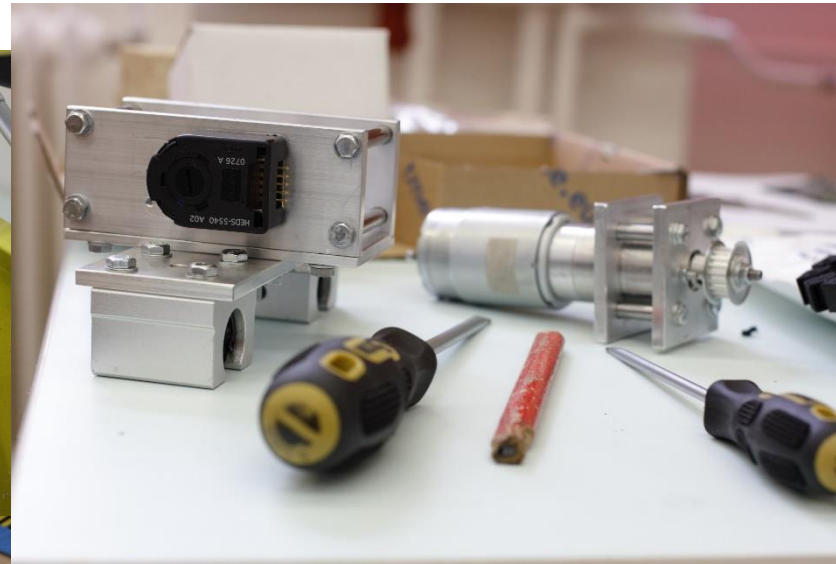
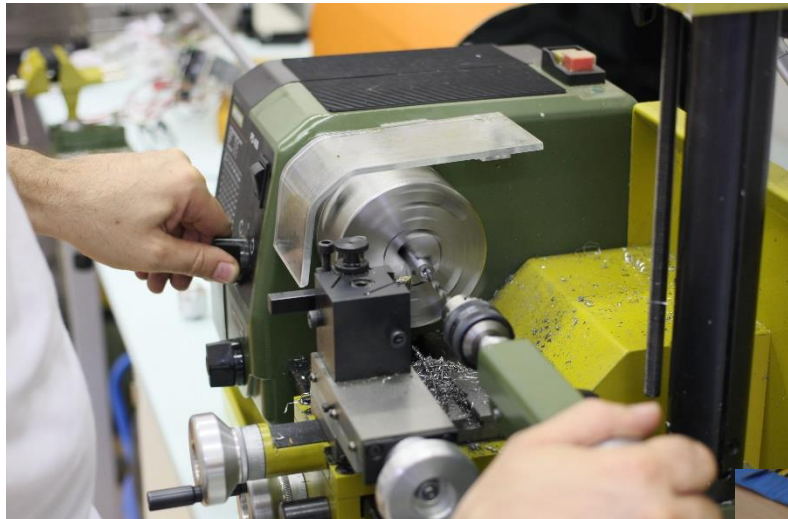


Prototyping workshop @ iROB

- Great inventory of **tools and equipments**
- Metal cutting
- 3D printing
- Plastic molding
- Electronics prototyping
- Full engineering support



Prototyping workshop @ iROB

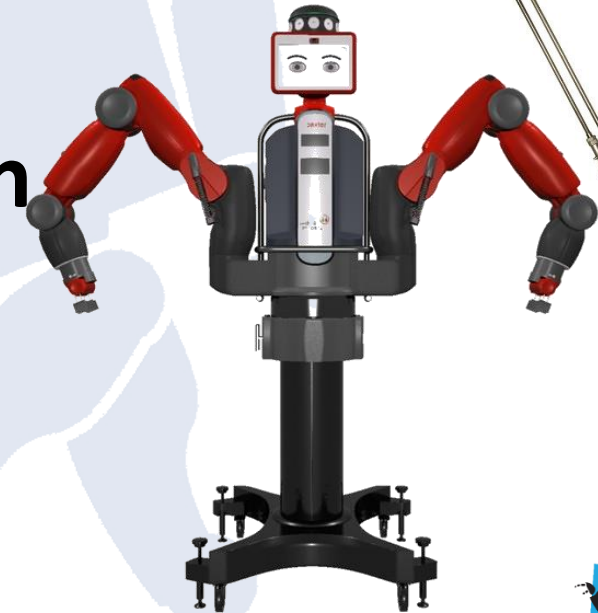


Evolution of Robots

Unimate 2000 series Robot



- **1960 – 1980** Early adoption
- **1980 – 1990** Going mainstream
- **1990 – 2010** Faster, Stronger, Smarter
- **2012 – Mobility, Collaboration, Cognition**



Cobotics



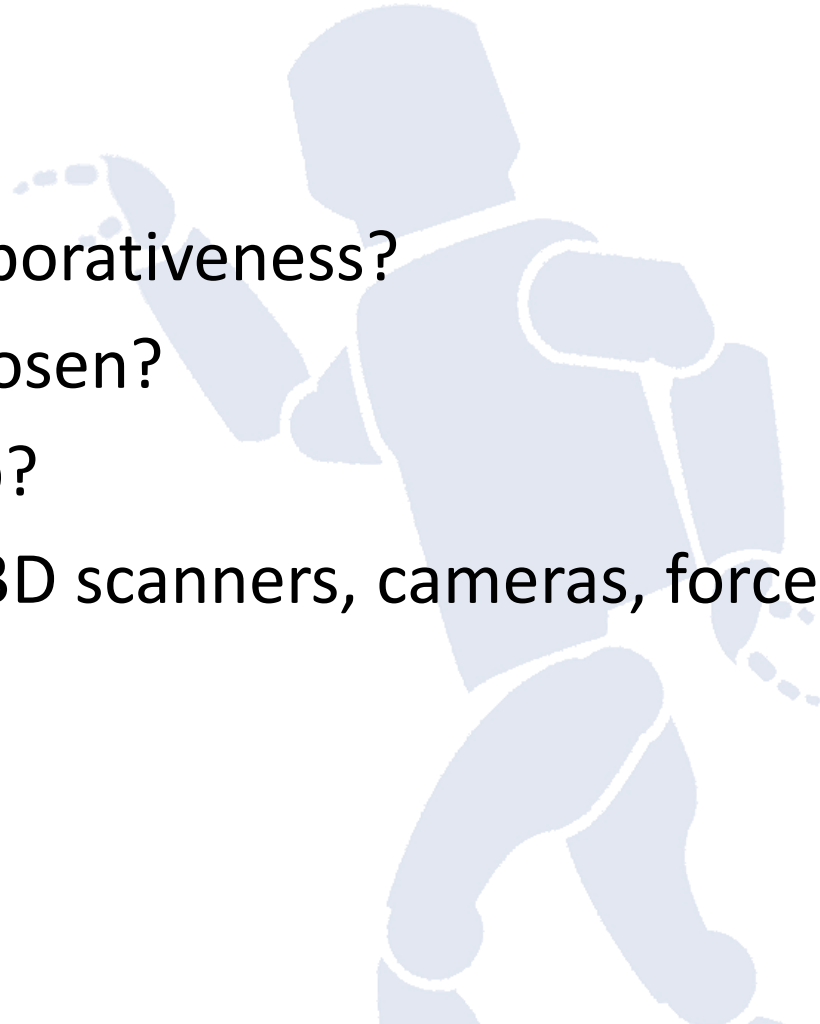
Pros and Cons

| Pros | Cons |
|--|---|
| Good ROI (~ 1 year in some cases) | Expensive safety devices (Laser scanners) |
| Fenceless operation | Still insufficient cognitive capabilities |
| Combine robot strength with human intelligence | Collaborative scenarios are typically slow |
| Increase productivity with the same human staff | Typically limited payload |
| Better reusability | Non-deterministic operation |
| Easier programming (e.g., direct teach-in) | Increasingly exposed to „sabotage“ |



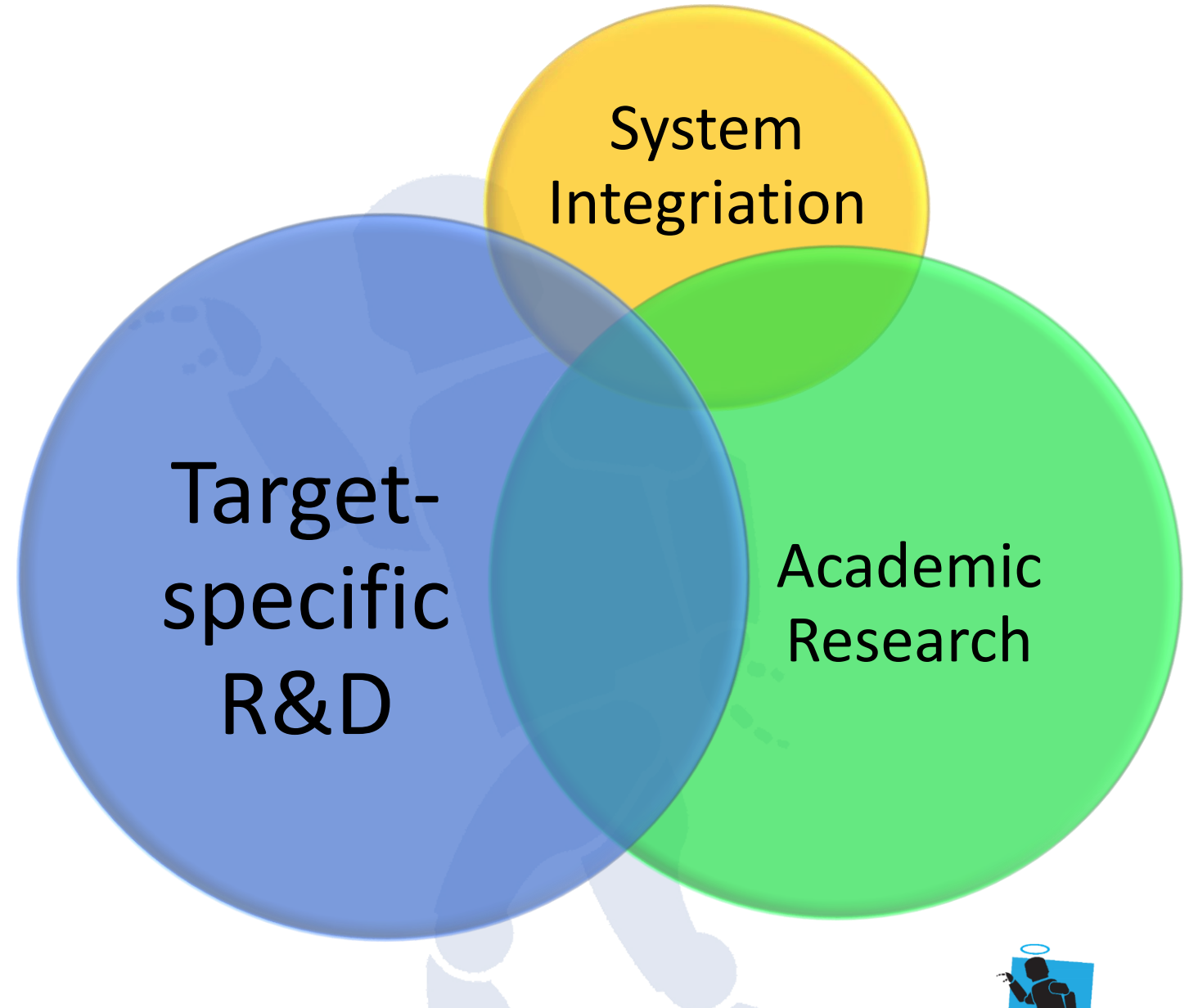
The value challenge in Cobotics

- Conventional or collaborative?
- What is the proper level of collaborativeness?
- What sort of robot should be chosen?
- How many robots can do the job?
- What kind of sensors needed? (3D scanners, cameras, force sensors, etc.)



Our business

- 6+ Dedicated research engineers
- Run min. 2 parallel Industrial projects
- Prototype manufacturing workshop in place
- Agile cycles
- Universal, FANUC, KUKA expertise
- Integration of I4.0 features (IoT, Big Data, Deep Learning, etc.)



Look ahead: What comes?

Mobile + limb

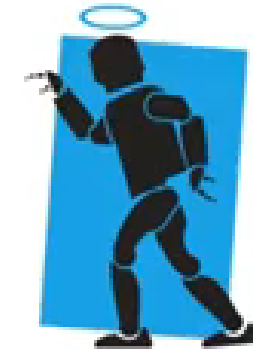
Deep learning



Superhuman
sensing



Application example – Force-based interaction



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